

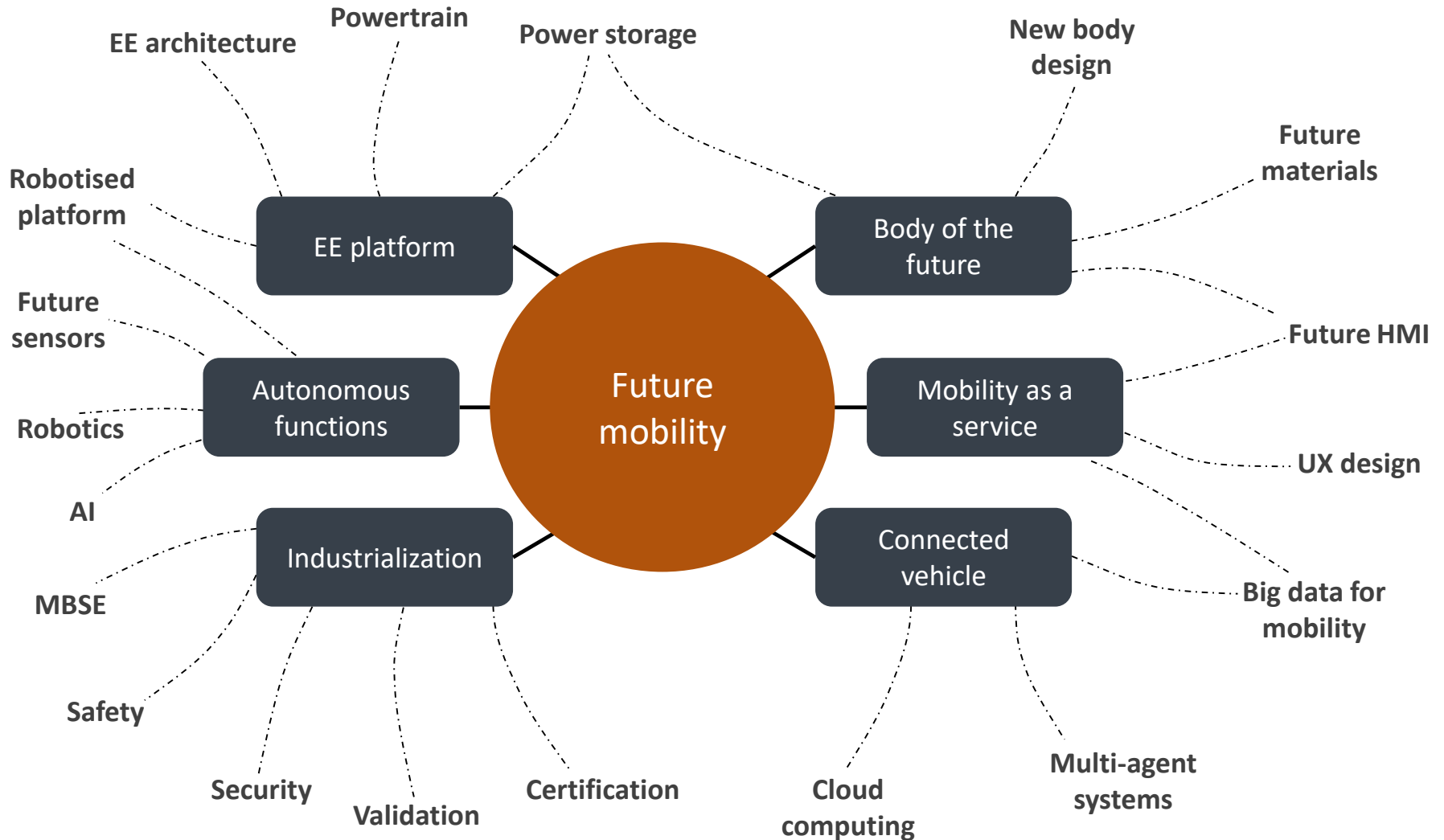


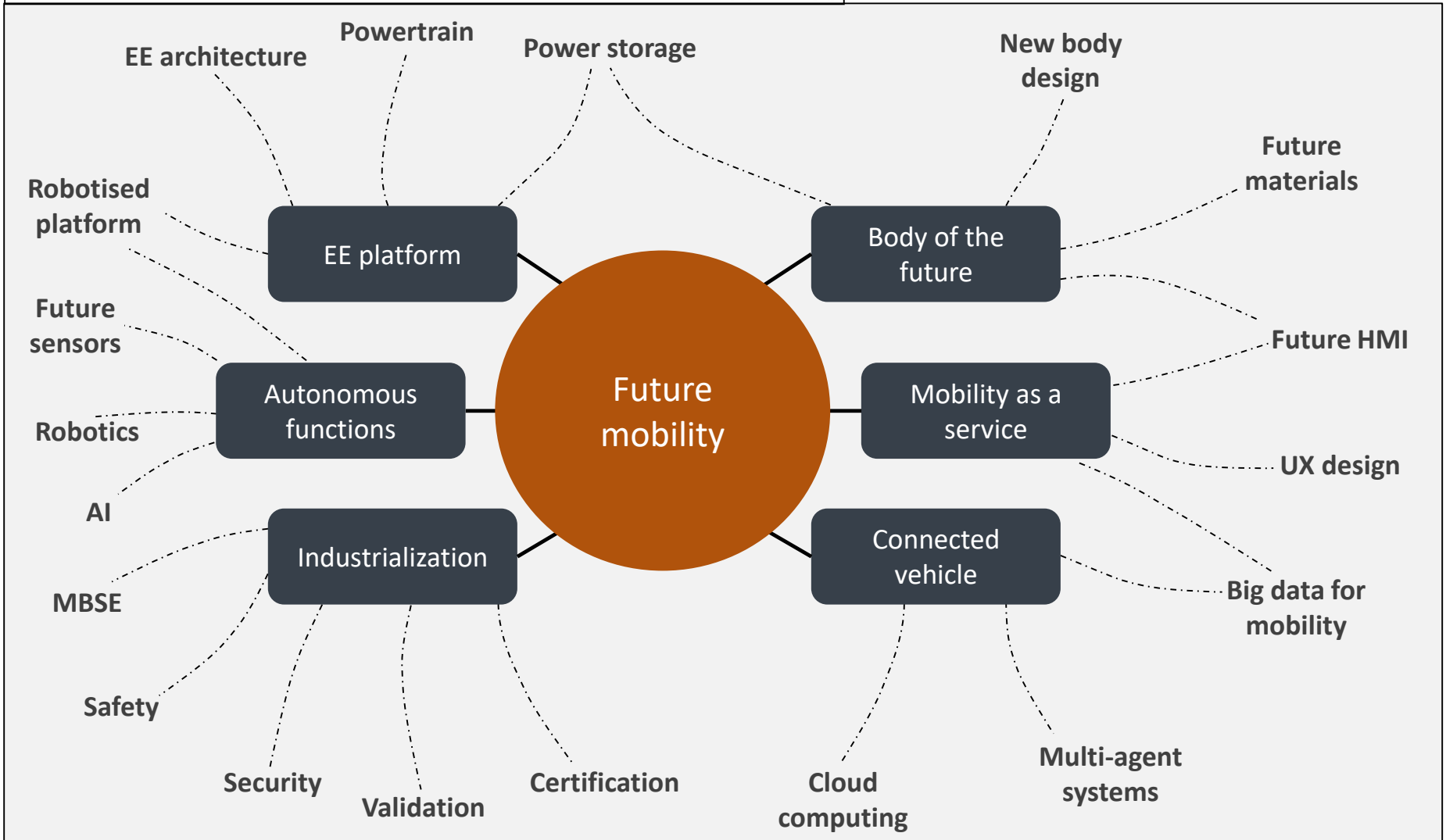
VALET project: how connected and automated driving will change urban parking ?

Proposition technique

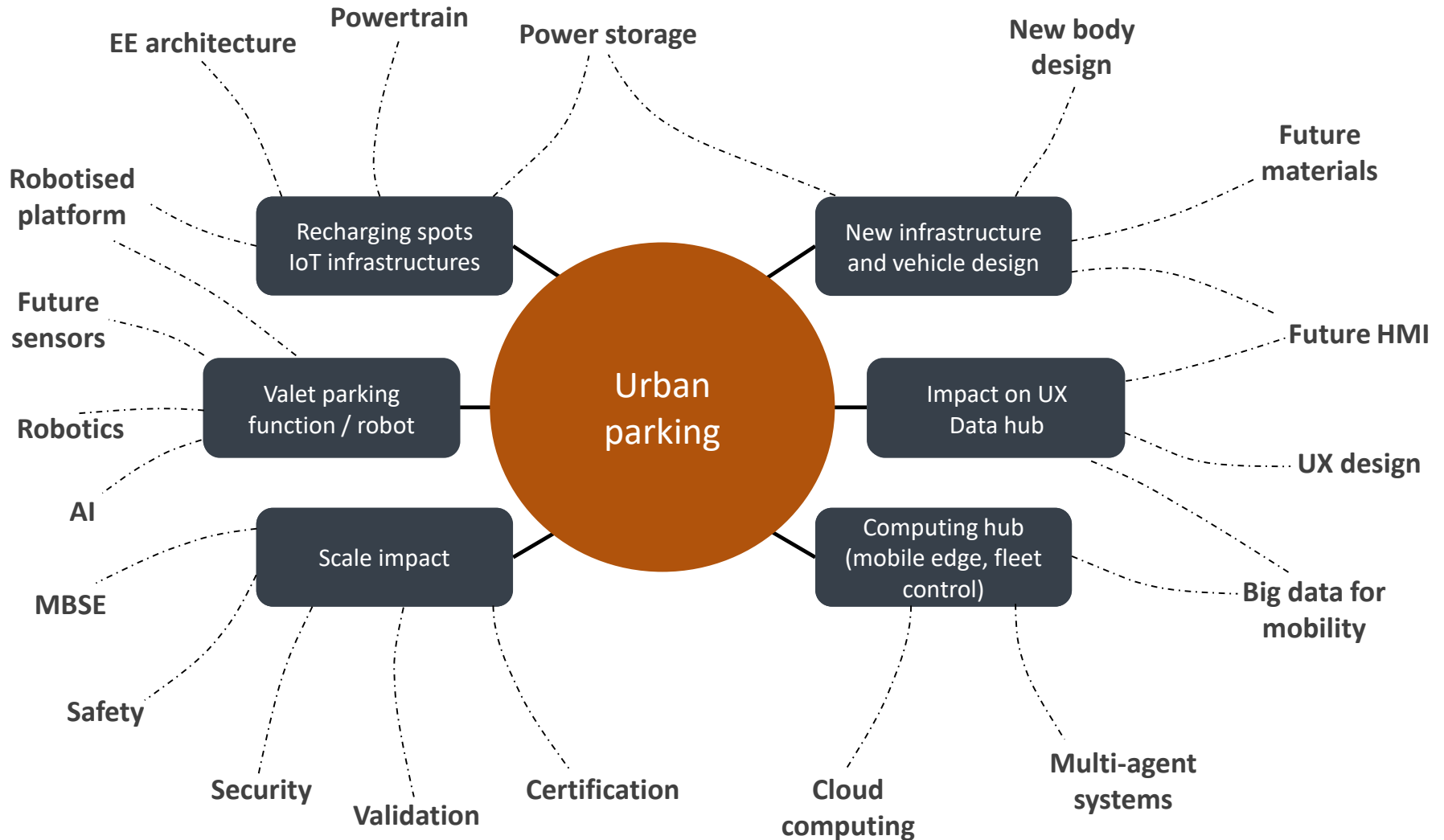


AKKA Vision on the future of mobility

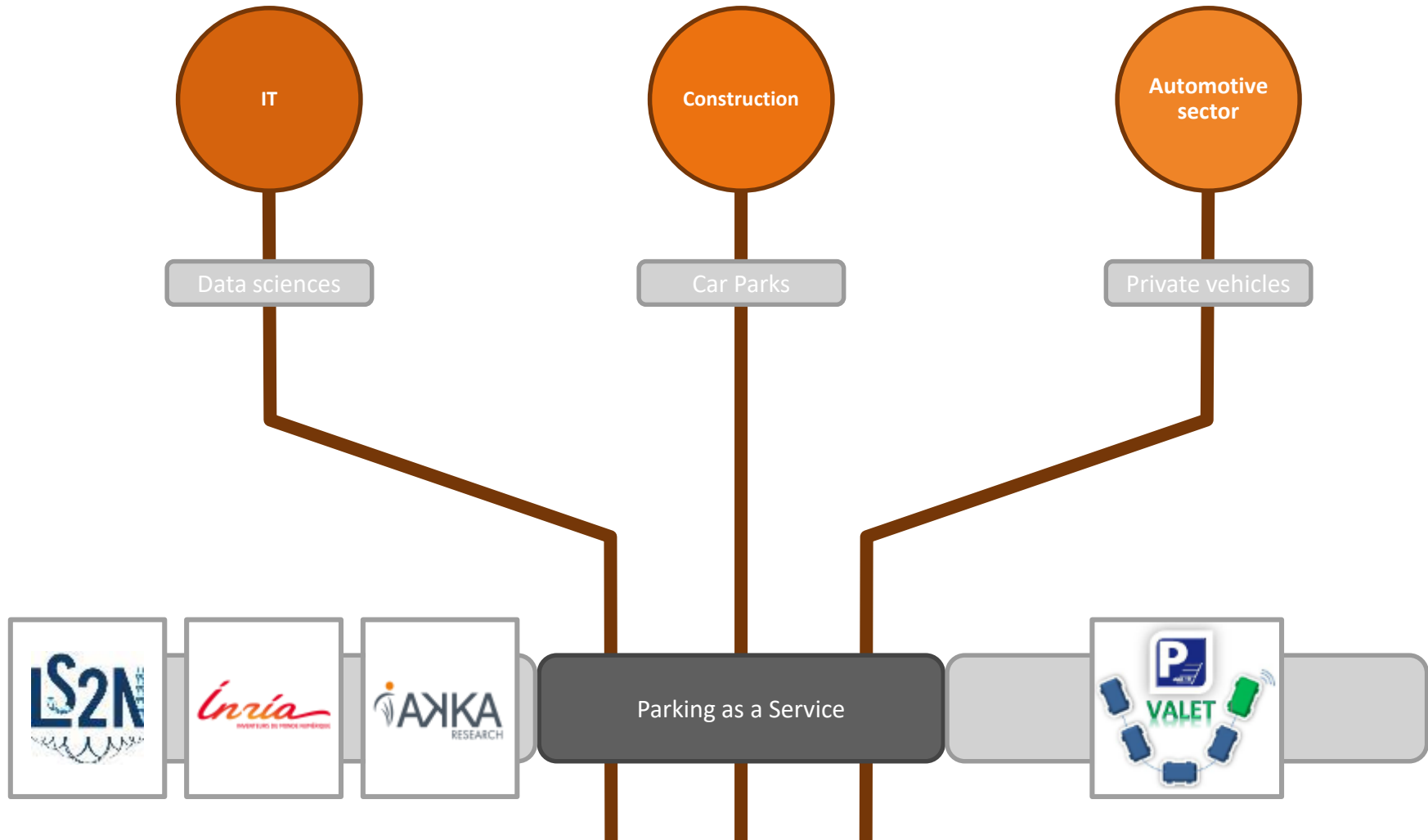




Urban parking: an incubator for urban mobility



Where IT & sector know-how meets



RESEARCH PARTNERSHIP VALET

CARRIED OUT
BY AKKA
RESEARCH

PROJET - CONTEXT

- For car-sharing systems, relocation strategies require more sophisticated techniques for their implementation on cities. As automatic relocation cannot be achieved for legal reasons, an alternative is to get a leader vehicle, driven by a human, which comes to pick up and drop off vehicles over the stations. VALET project proposes to endow autonomous vehicles with smart behaviors (cooperation, negotiation, socially acceptable movements) that better suit complex urban situations.

OBJECTIVES

- VALET project aims to find a solution through the development of an intelligent and efficient redistribution system that applies all cars including electric vehicles.

TASKS & REALIZATIONS

- Definition of global architecture and interaction between component of the solution
- Definition/conception and realization of operator MMI
- Realization of parking management system (including algorithm and MMI).

PARTNERSHIP



Future of mobility – AKKA’s projects overview

	Detect and exchange with the infrastructure	Autonomous supervision	User friendly autonomous driving	Pre-industrialization of autonomous vehicles	Industrialization of Autonomous functions
AKKA's investments	3D reconstruction and segmentation	Multimodal trajectography and control	Autonomous vehicles HMI	Safe embedded electronics	
	Simultaneous localisation and mapping	Machine learning and scene understanding	Accurate control	MBSE for autonomous vehicles	
	Functionnal Validation				
PhD	 	 		 	
Funded projects	 	 		 	



Contact :

Guillaume Trehard, guillaume.trehard@akka.eu

